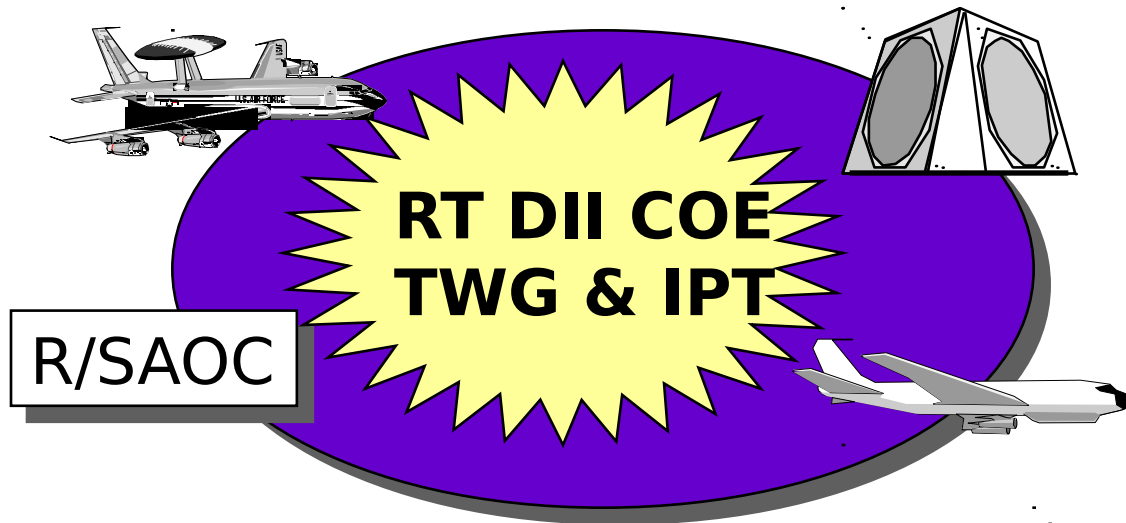




Real-time DII COE Enables Real-time Technologies

http://www.dii.af.hanscom.af.mil/infrastructure/COE/rtipt/rtipt_hm.htm



John Maurer
TWG Chair
781-271-2985
johnm@mitre.org

Lt Col Lucie Robillard
IPT Chair
781-377-2679
robillardl@hanscom.af.mil

Outline



- **EAF C2 Architecture**
- **C2 Weapon System Spectrum**
- **Data Criticality - Real-time Needed?**
- **RT DII COE Accomplishments**

EAF C2 Architecture



En-Route C2



Collaborative tools



Distributed Ops JAOC-Fwd



Distributed Ops JAOC-Rear (BOCC)



En-Route Msn Planning and Re-targeting



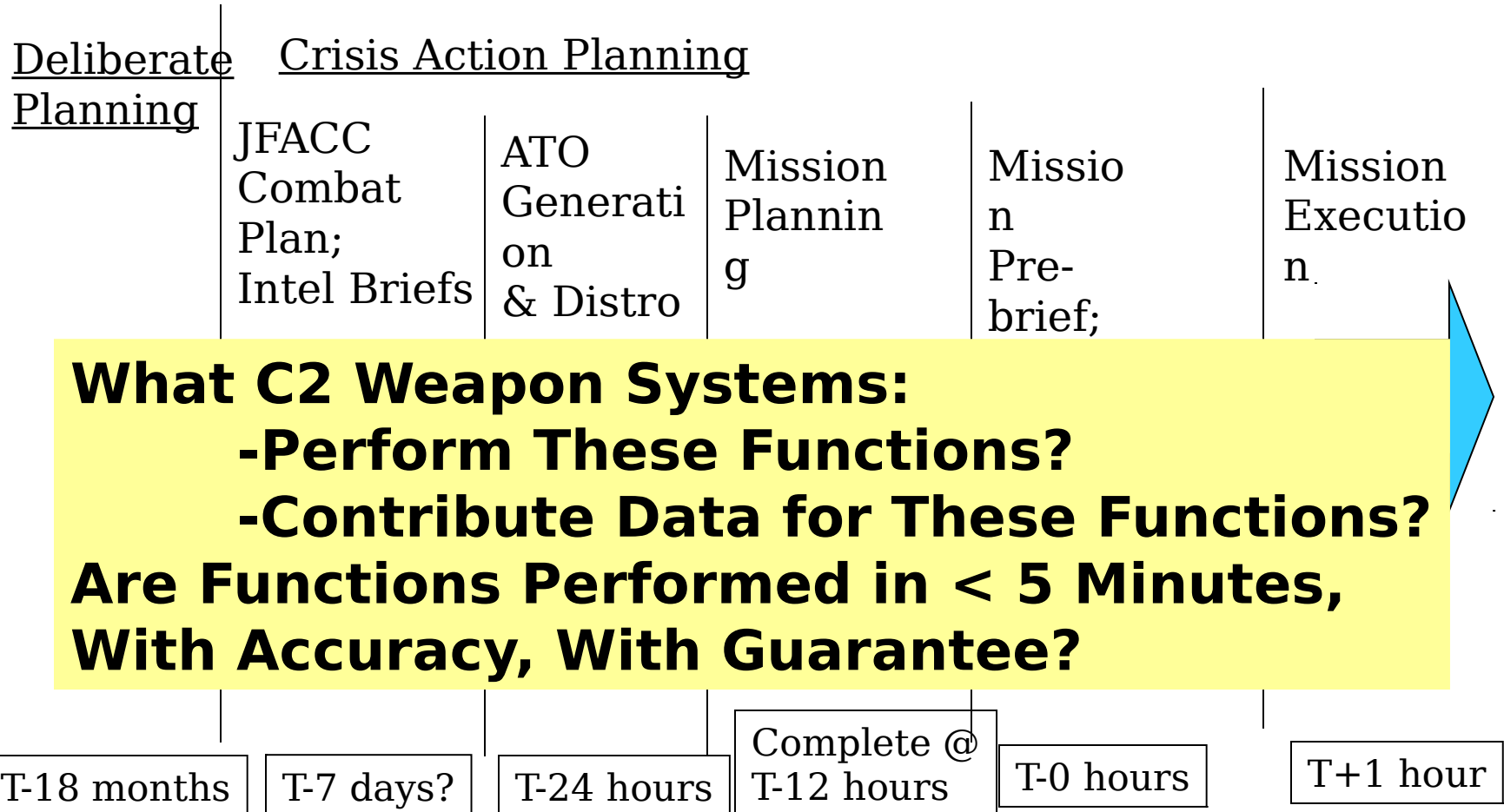
Sensor-to-Shooter

Sensor-to-Decision Maker-to-Shooter

EAF Key Elements - People, Processes and Systems

C2 Weapon System Spectrum

Air Mission Example



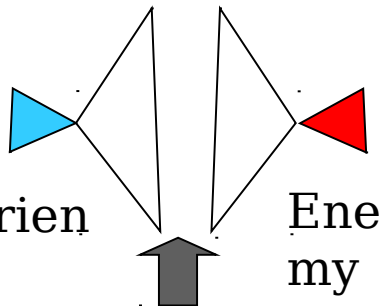
C2 Weapon System Spectrum

Air Mission Example

Mission Execution: A-A, A-G,
SEAD

Surveillance Area

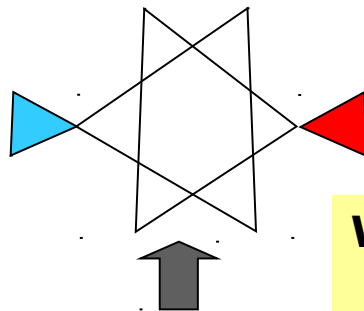
Detect ID



Outside
Weapon
Parameters

T- Seconds

Weapons
Engagement
Zone

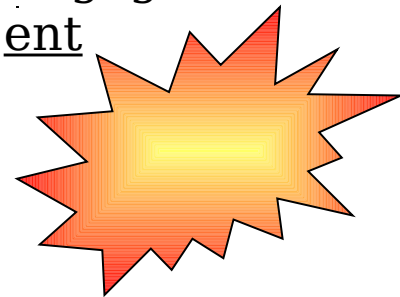


Within
Weapon
Parameters

T- Seconds

Committ

Engagem
ent



What C2 Weapon Systems:

-Perform These Functions?

-Contribute Data for These Functions?

**Are Functions Performed in < 5 Minutes,
With Accuracy, With Guarantee?**

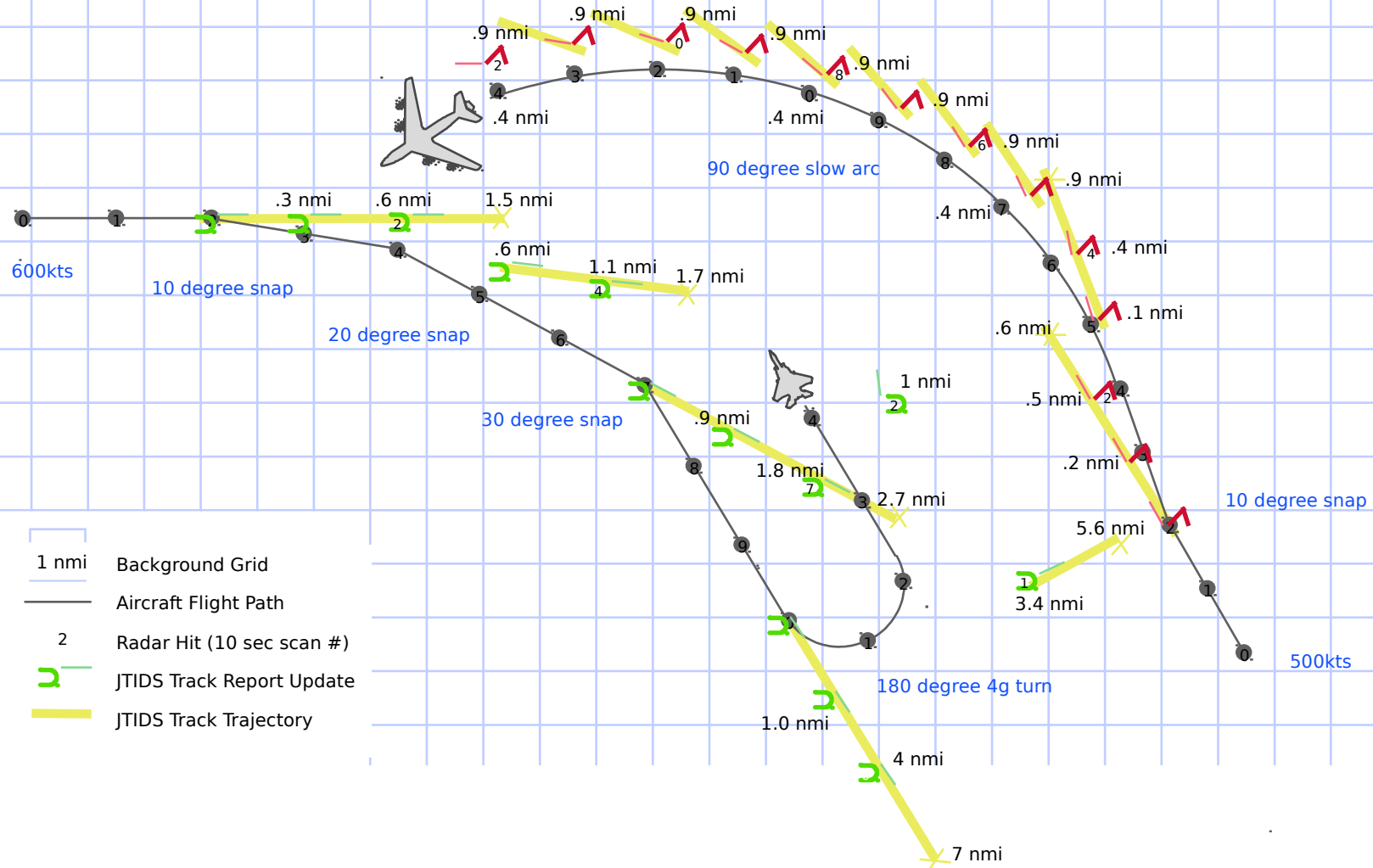
T- Seconds

T - 0

24 **Key Factors: Accuracy of Time Stamp & Data ; NO Stale Data**

Is the Data You Are Providing Time Critical? Impacts of Delay: 20-30 Sec Data Latency

With perfect tracking (i.e., position/heading/speed reset to true each radar scan)
With perfect reporting and reception (i.e., updates received every 10 sec)



When Do You Know You Need Real-time (RT)?

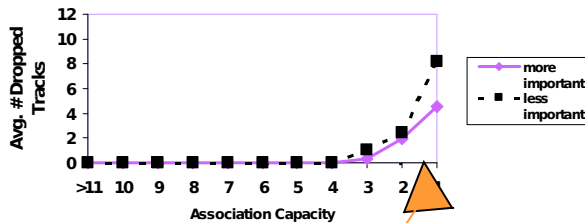
- **Game of Deadlines**
 - Rule of Thumb: RT = Milliseconds --> 5 Minutes
 - What # Deadlines Feed the 'Decision Process'?
 - C2 Data Flow (Human) & C2 System Processing (Automated)
 - Is Deadline Guarantee Important?
 - What # of Misses Can Be Tolerated?
 - What are the Consequences of One (or More) Misses?
 - What Timeframe for Next Update?
- **Some Sources of Deadline Misses:**
 - Method of On-Board Data Processing
 - Choice of Priority Scheduling Policy
 - FIFO, Fixed, Dynamic

Design Considerations That Impact RT Data

Differences In FIFO, Fixed, and Dynamic Priority Scheduling

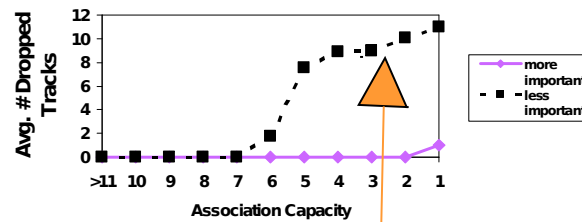
FIFO

Avg. # Dropped Tracks versus Association Capacity For FIFO Priority



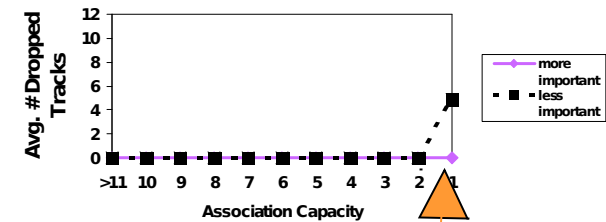
Fixed

Avg. # Dropped Tracks versus Association Capacity For Fixed Priority



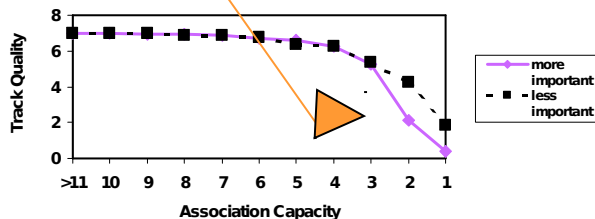
Dynamic

Avg. # Dropped Tracks versus Association Capacity For Dynamic Priority

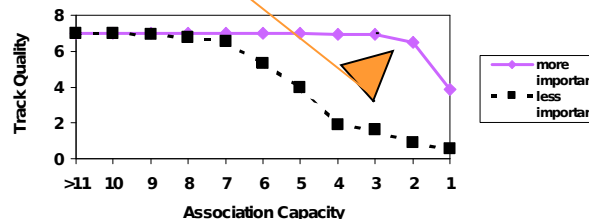


High Priority Tracks Go Dropped and have Bad TQ on *High Priority* Tracks Dropped.
 Drop Low Priority Tracks to Get Better TQ on *High Priority* Tracks Dropped.
 Overall Better TQ

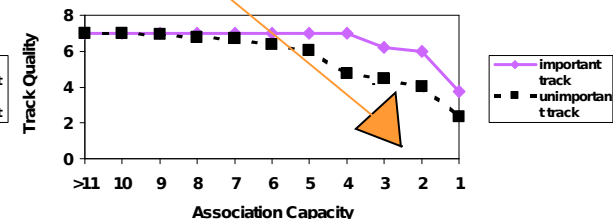
Track Quality versus Association Capacity For FIFO Priority



Track Quality versus Association Capacity For Fixed Priority



Track Quality versus Association Capacity For Dynamic Priority



Key:

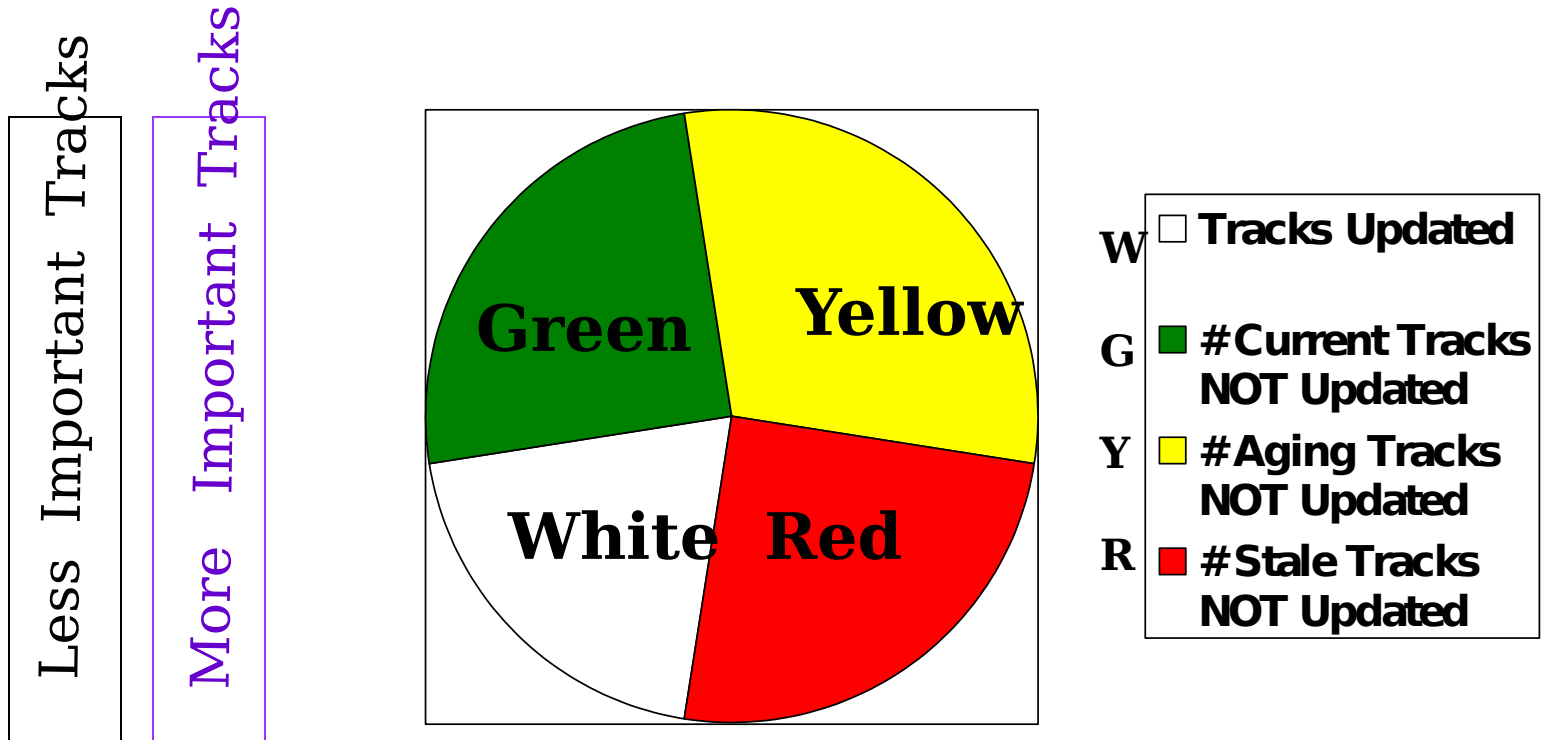
Track Quality: 0-7 (7 = Ideal)
Association Capacity = # Tr
Processed under Constraint

FIFO: TBMCS

FIXED: AWACS, JSTARS, R/SAOC, CM

Demonstration Display

Screen Explanation



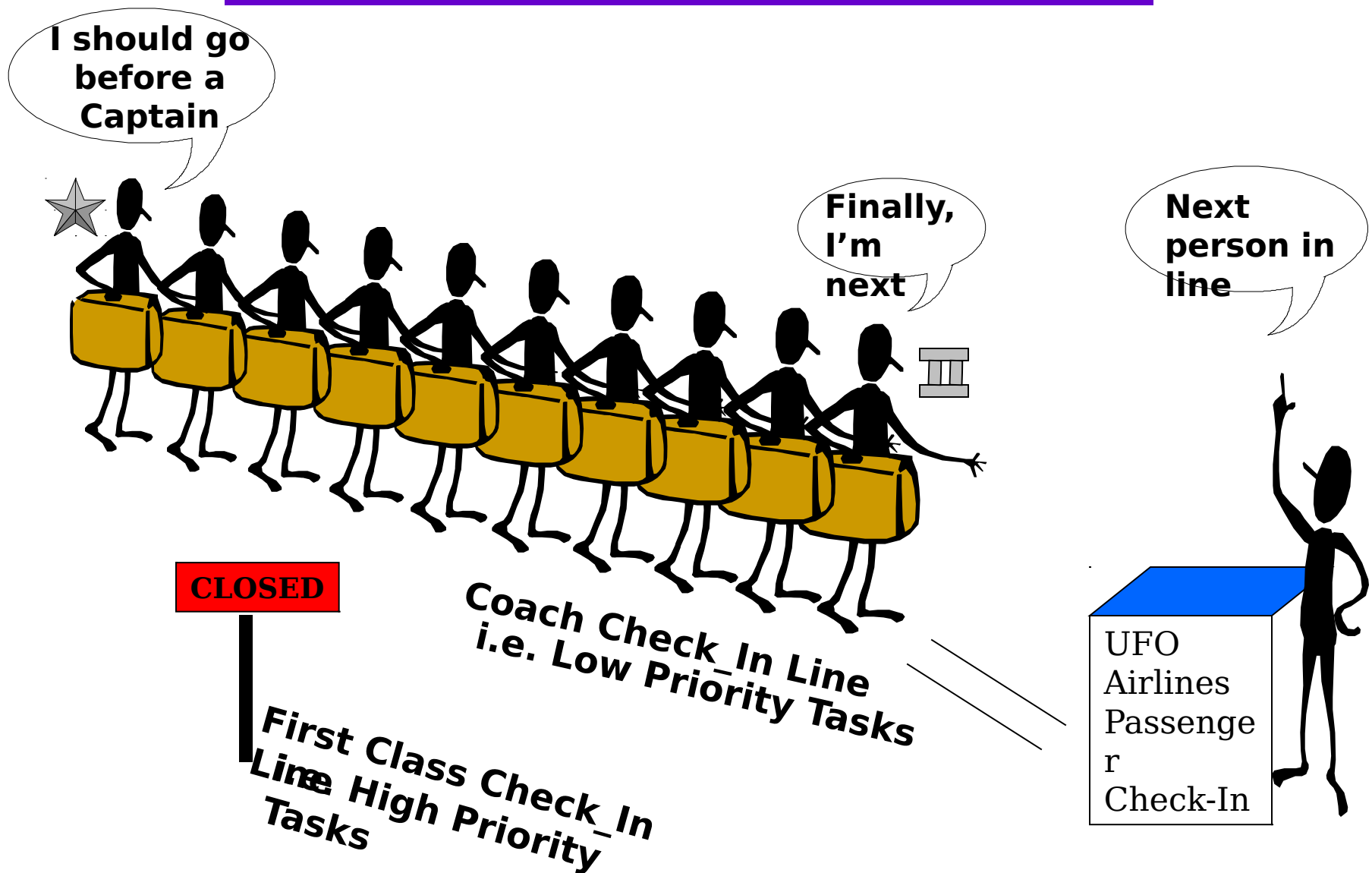
Quality of Track Estimate

Confidence in

All Tracks NOT Updated

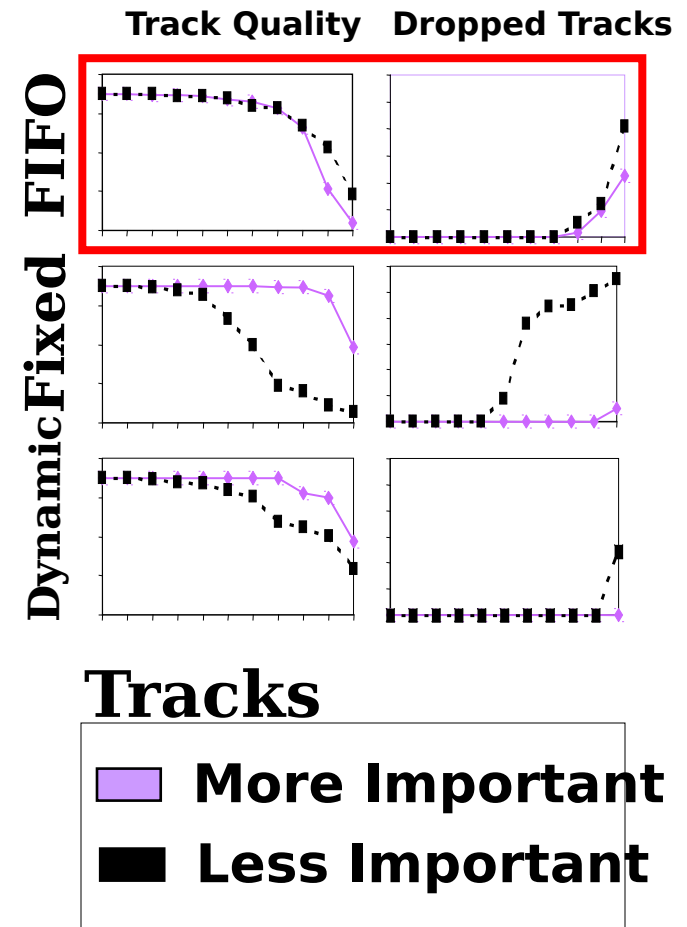
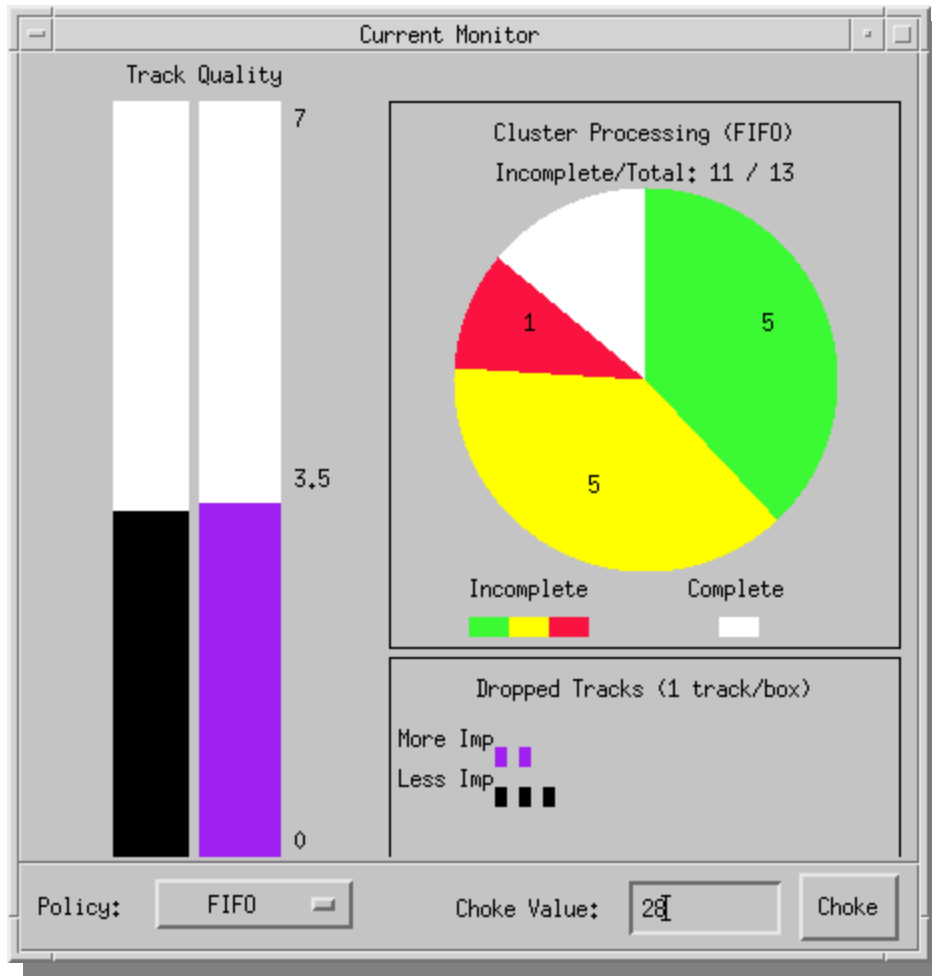
(Perfect Track = 7)

First-In / First-Out Scheduling



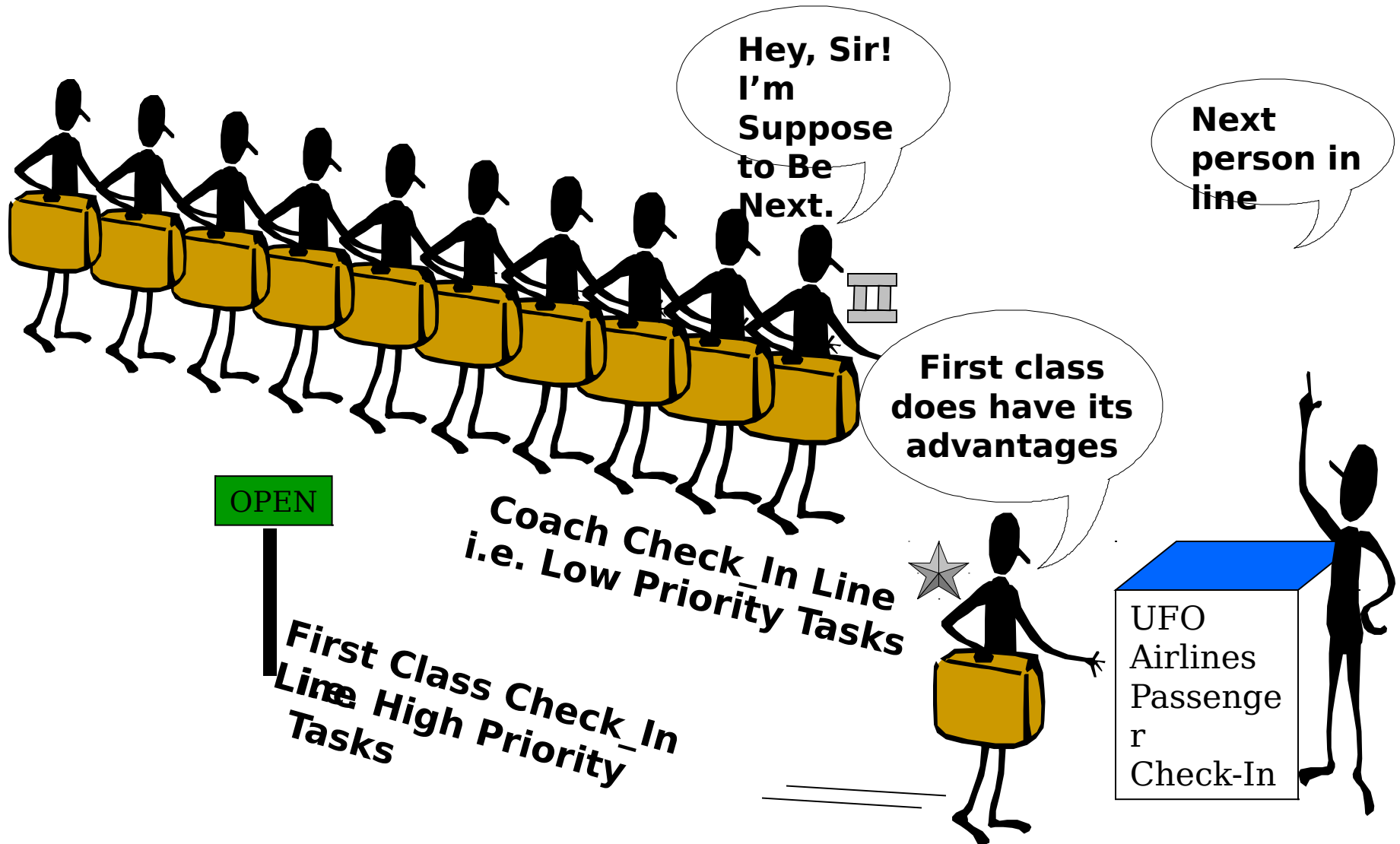
Typical Display and Results:

FIFO Scheduling



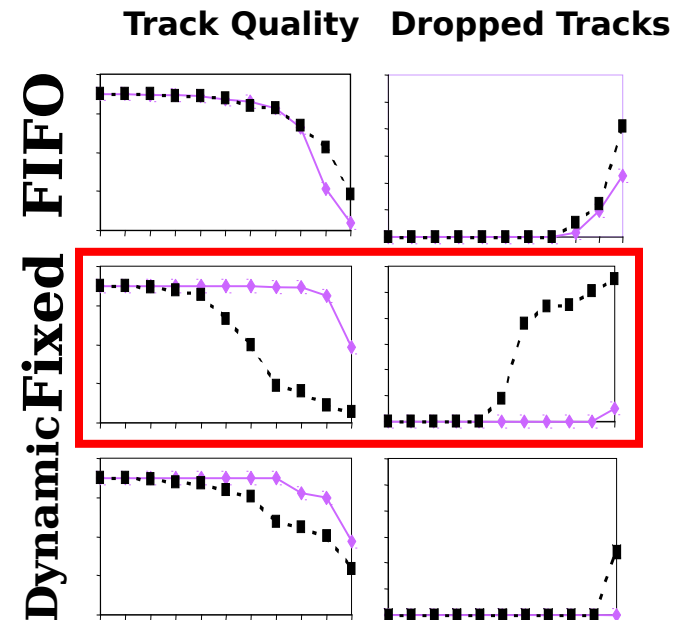
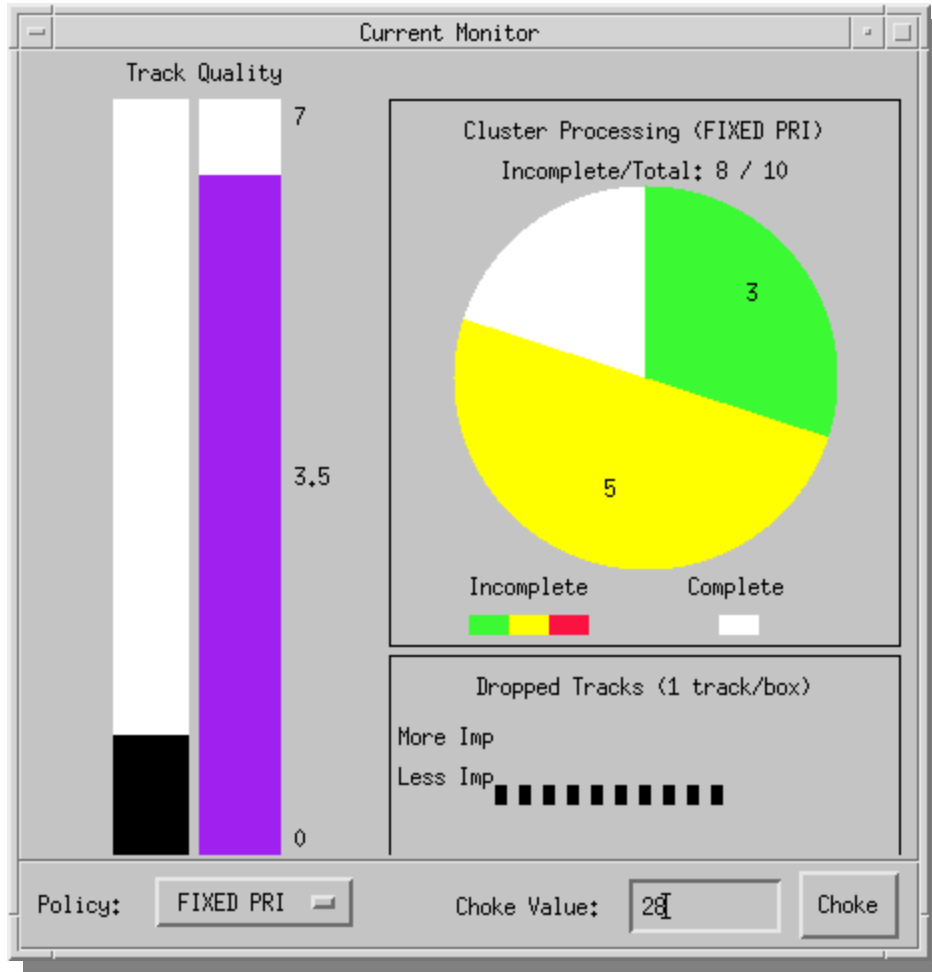
High Priority Tracks Got Dropped--Increased Operator Work

Fixed Priority Scheduling



Typical Display and Results:

Fixed Priority Scheduling

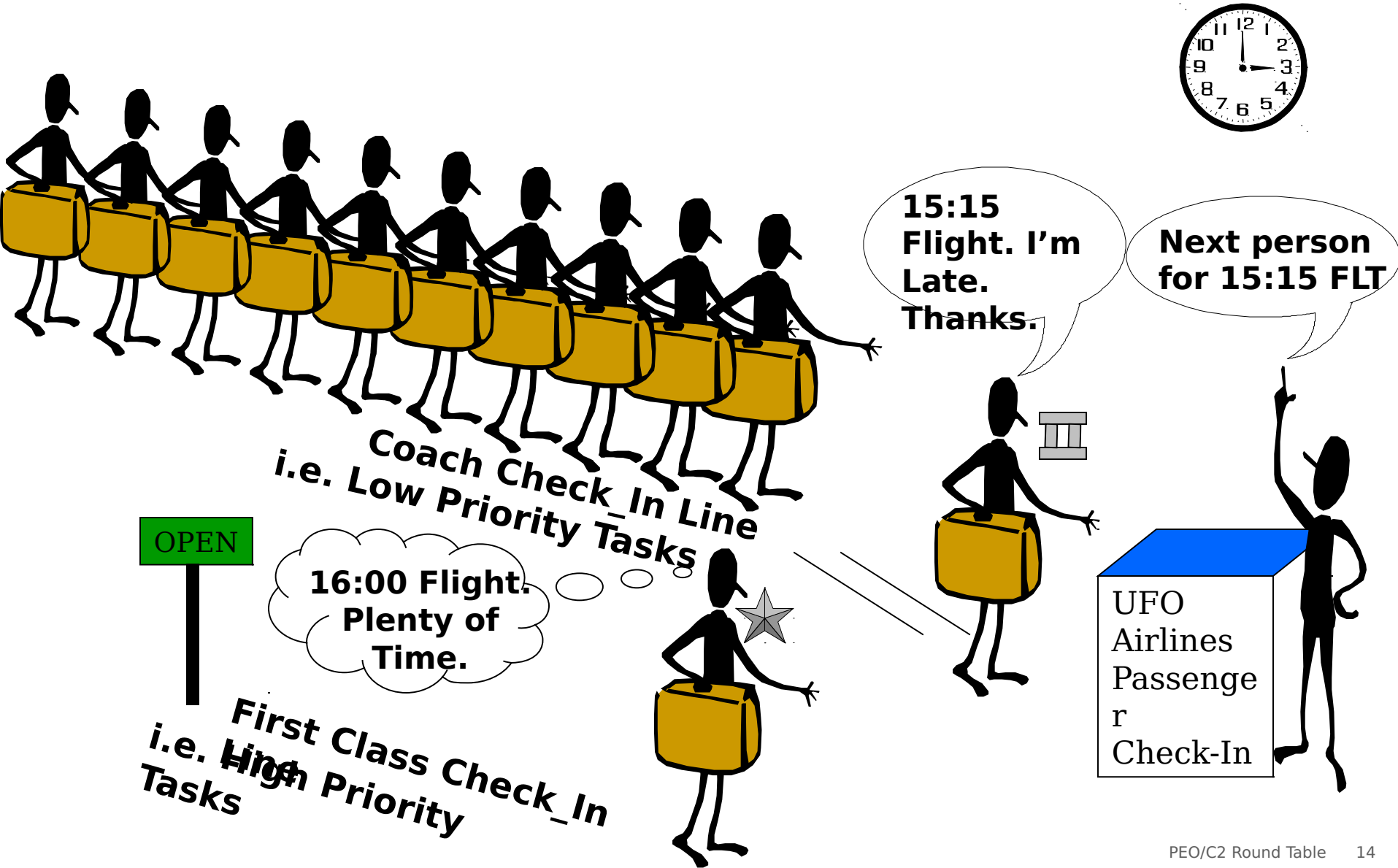


Tracks

 **More Important**
 **Less Important**

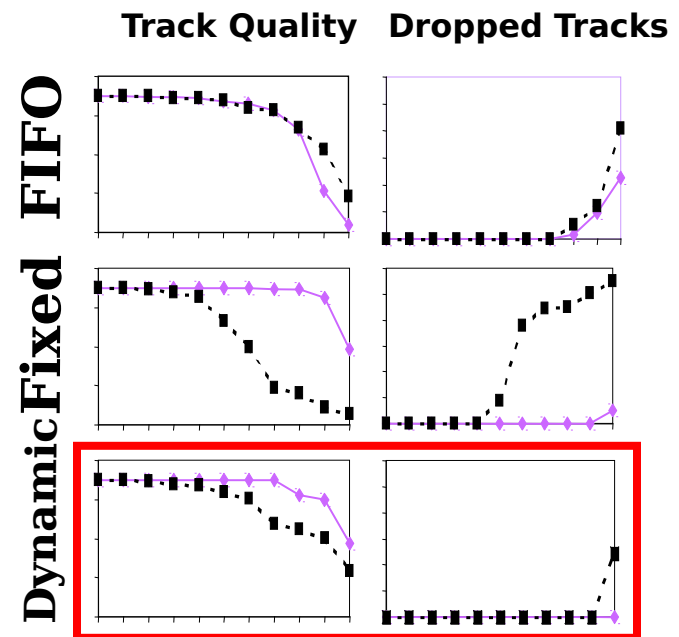
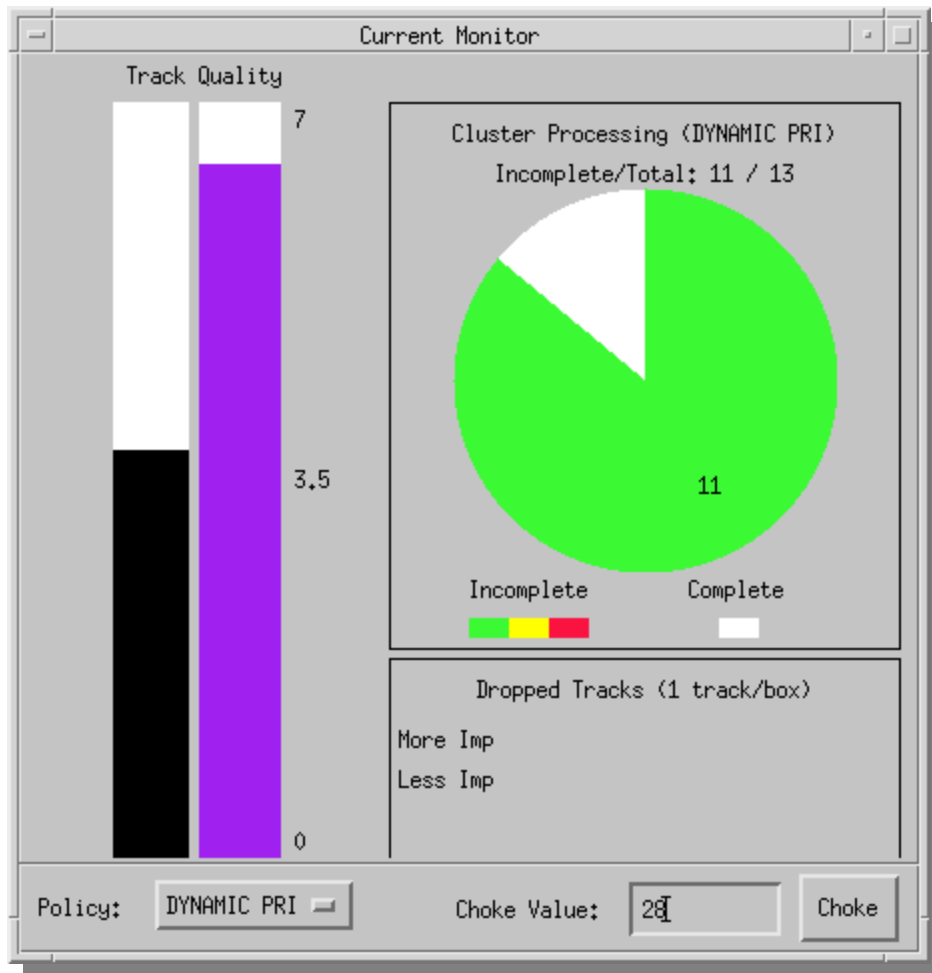
High Priority Tracks Got Processed--BUT Decreased Situation

Dynamic Priority Scheduling



Results:

Dynamic Priority Scheduling




Tracks

More Important
Less Important

No Tracks Got Dropped -- Operator Workload Op

Which Scheduling Choice Today?



- **Hurdles to Dynamic Priority Approach**
 - **Research Project! Engineering Theory Since 1973**
- **Fixed Priority Approach Can Be Better for Real-time**
 - **Detailed Analysis Required -- Its Tough!**
 - **Ad Hoc Approach Typical: “Always Done That Way”**
 - **Real-time Scheduling Disciplines Required**
 - **Understand Timing Behavior of Applications**
 - **Preserve Correct & Consistent Data**
- **FIFO is DII COE Approach**
 - **Not Good Enough for Most C2 Systems**

Make Fixed Priority Scheduling a DII COE Option

Relevance to RT DII COE Activities

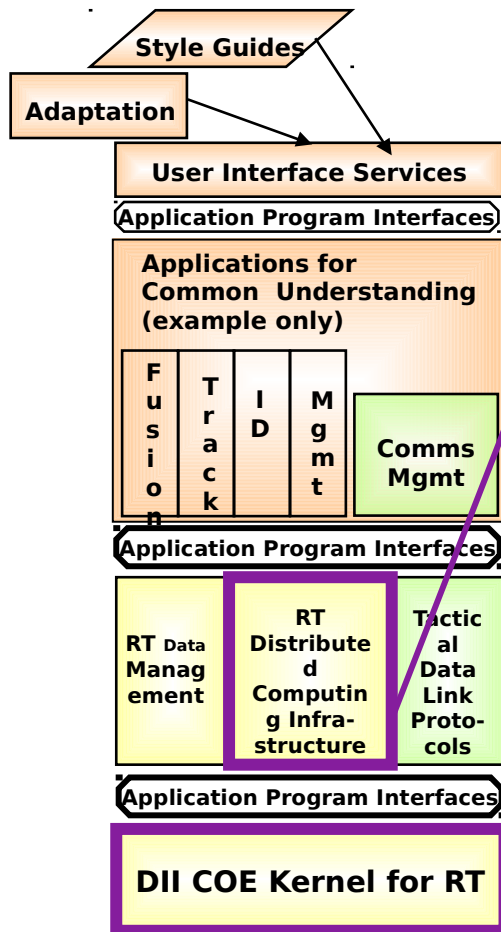


- **Demo Showed Improvement in Mission Performance Using Real-time Technologies**
 - Theoretical Basis for Improving on “The Way We’ve Always Done It”
- **RT DII COE Provides the Real-time Foundation To Implement Real-time Technologies**
 - **RTOS and RT Infrastructure Supports:**
 - Predictable Timelines, Priority, and RT Scheduling
 - **Configurable RT Kernel**
 - Make Dissemination of Future RT DII COE Segments Easier

RT DII COE is the Enabler for RT Approaches

RT DII COE Accomplishments

Technology That Enables Dynamic Scheduling



RT Common Object Request Broker (RT CORBA) for Distributed Computing

- Lockheed Martin's HARDPack as candidate initial product
 - HARDPack 1.3 or later
 - RT extensions

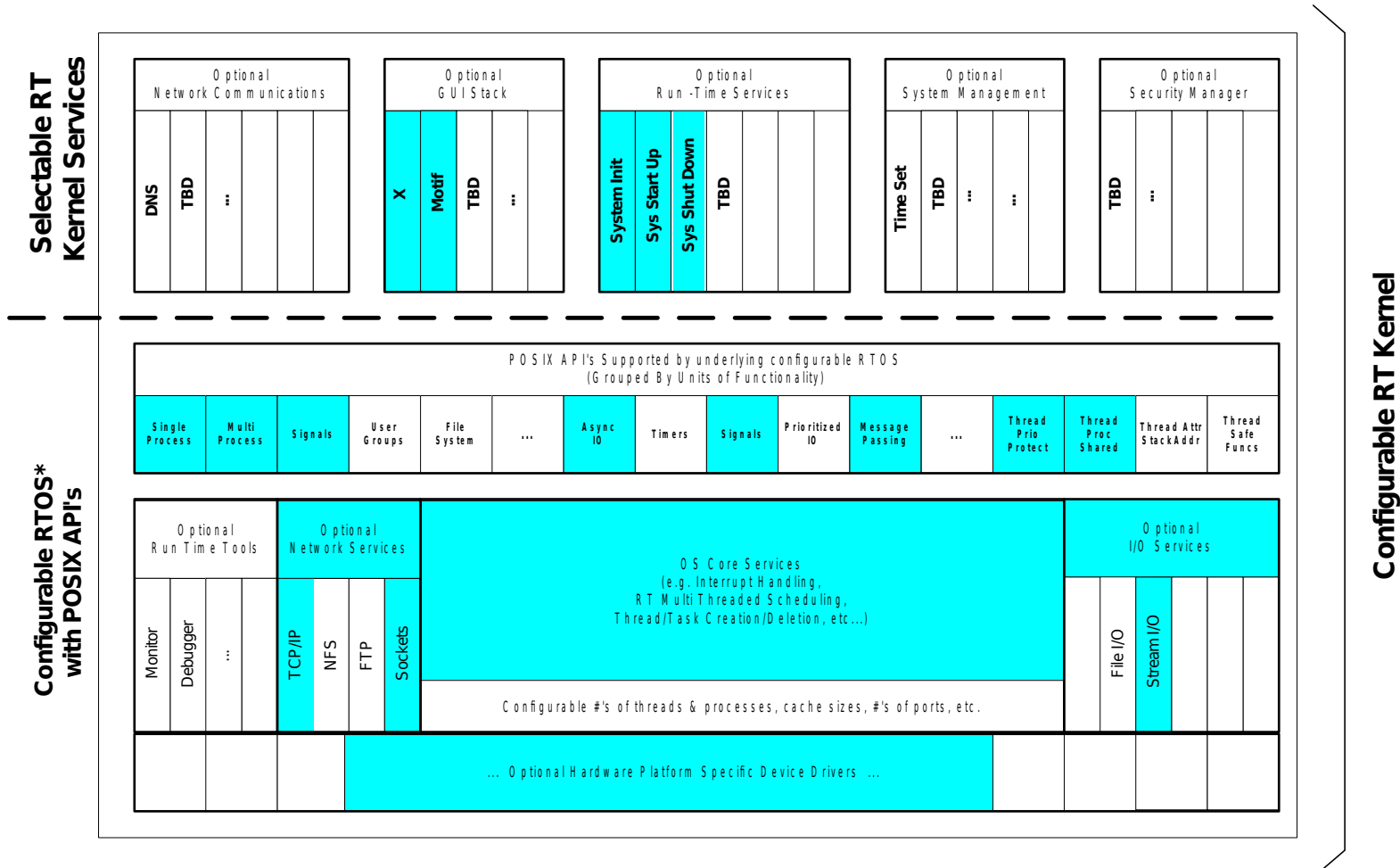
Configurable DII COE RT Kernel Available for LynxOS, Solaris

- **POSIX APIs for Real-time OS**
 - LynxOS in reference implementation
- RT appropriate capabilities
- Selectable Kernel Services
 - Not monolithic kernel
- Configuration from RTOS up
- RT "Stickers" for mixing, matching applications to OS,

Will be in DISA Release 5.0, October 2000

RT DII COE Accomplishments

Configurable RT DII COE Kernel



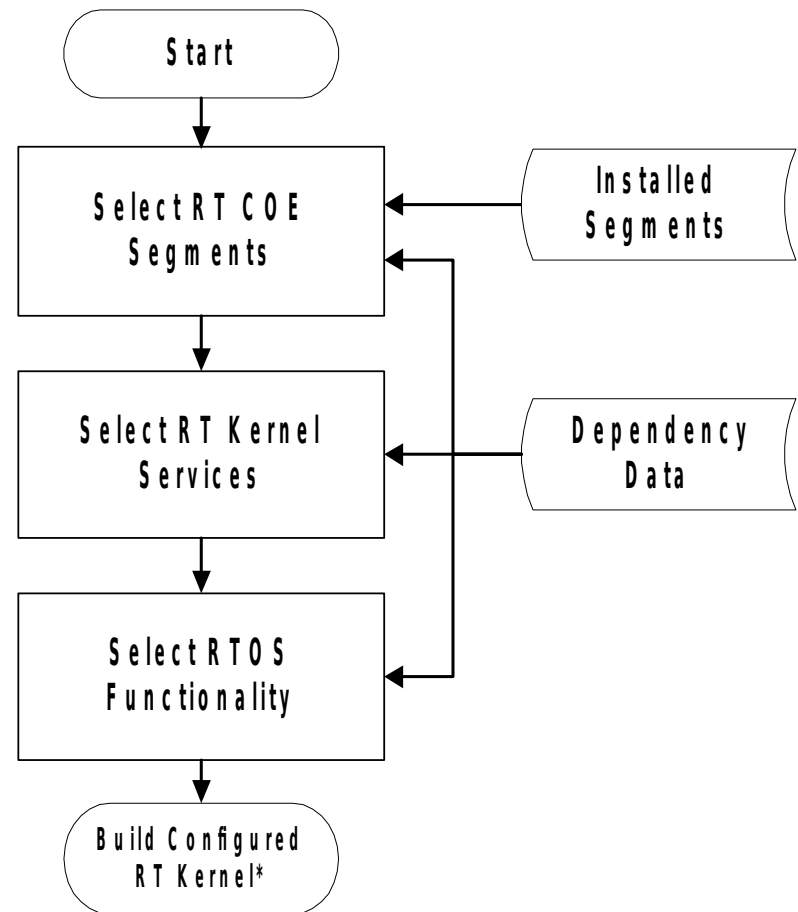
*Actual OS configuration depends on packaging options provided by RTOS vendor

RT Systems Are NOT One Size Fits All

RT DII COE Accomplishments

RT Kernel Configuration

- Integrator specifies list of segments (required capabilities)
- Each segment requires:
 - Other segments
 - RT Kernel Services
 - POSIX.13 API's
- Each RT Kernel Service requires:
 - Other RT Kernel Services
 - POSIX.13 API's



The Process to Build RT C2 System Using RT DII C

What do C2 System SPOs Do Now?



- **SPD Challenge**
 - **Determine Need for RT Techniques**
 - **Priority, Preemption, Predictability**
 - **If YES,**
 - **Identify Common Functions Among Your C2 Node Partners in Accomplishing Your Mission**
 - **Provide C2 Requirements to RT TWG**
 - **Advocate Common Capabilities Into DII COE via RT IPT**

RT DII COE: Path to C2 Interoperability

Conclusion



- **C2 Spectrum Being Defined**
- **RT Characteristics to Be Aware: Priority, Preemption, Predictability, Determinism**
- **Make DII COE Support Fixed Priority Scheduling**
- **SPD Challenges: RT and Common Functions**
- **RT DII COE Effort Is Making Progress**
 - **Become Part of the Team!**

RT DII COE a Reality: Oct 2000
RTOS, Selectable RT Kernel Services, RT CORBA